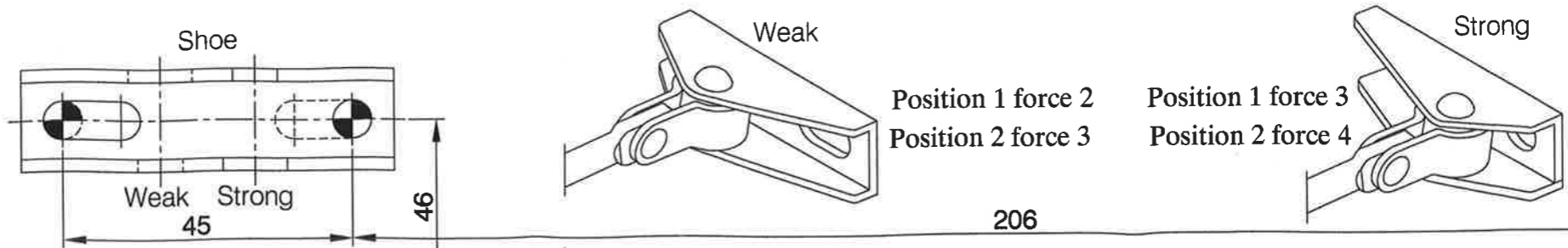


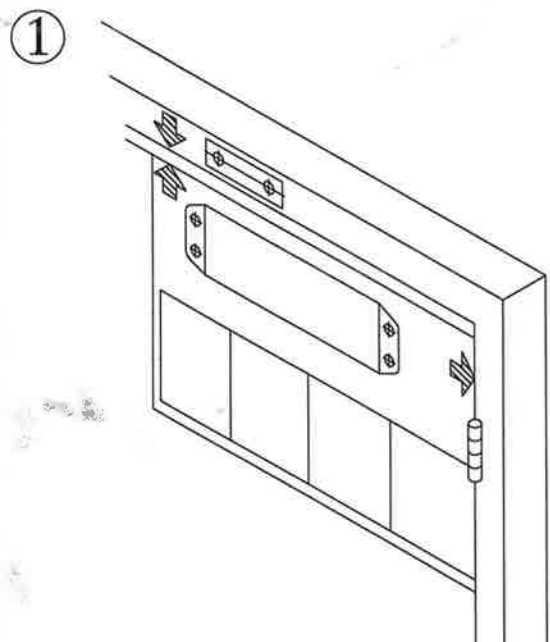
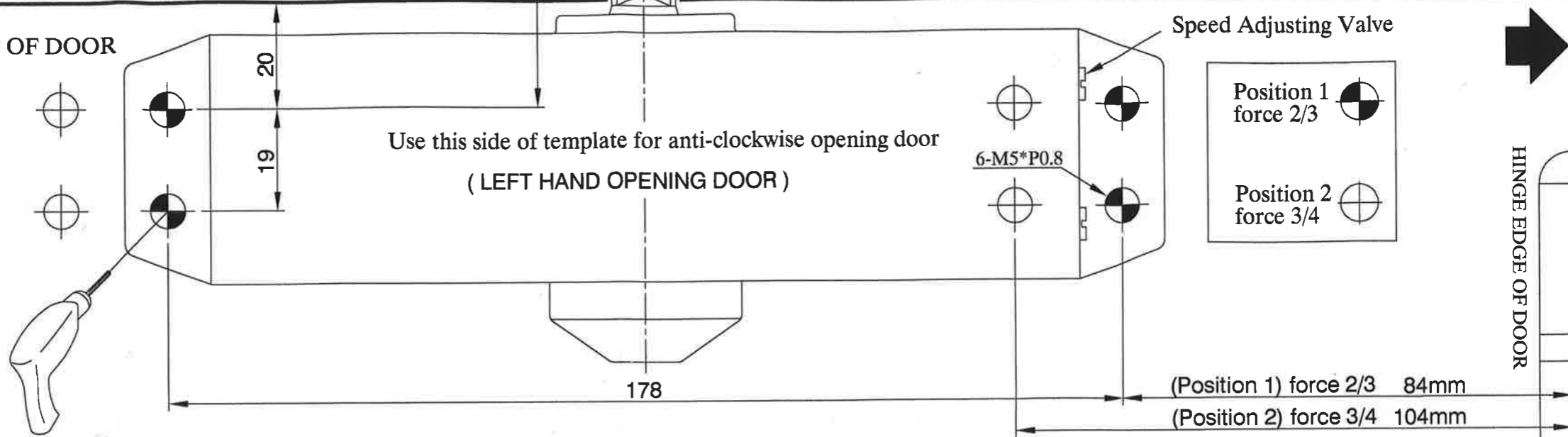
DETERMINE POSITION OF SHOE FROM CHART OPPOSITE AND FIX ACCORDINGLY



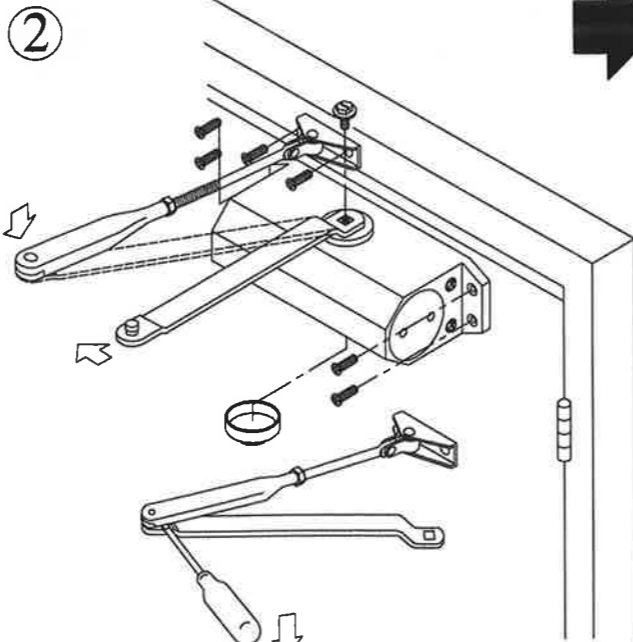
UNDERSIDE OF FRAME

SET TO TOP OF DOOR

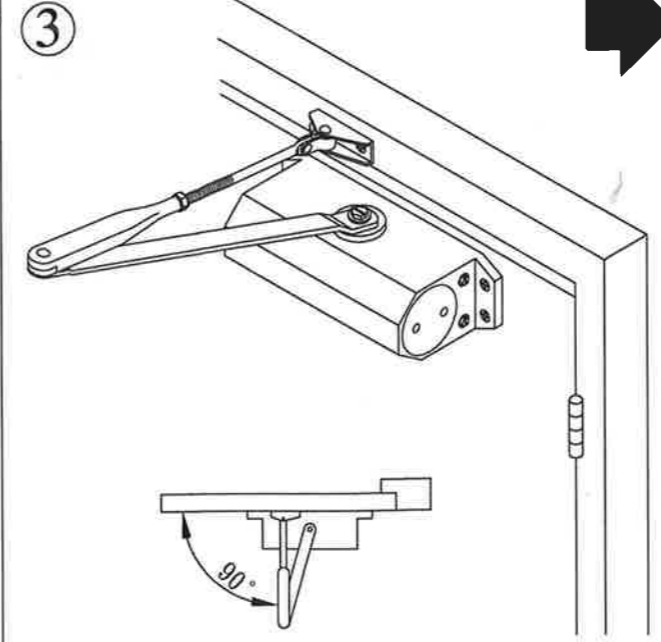
Ø4.2	Ø2.5
M5	



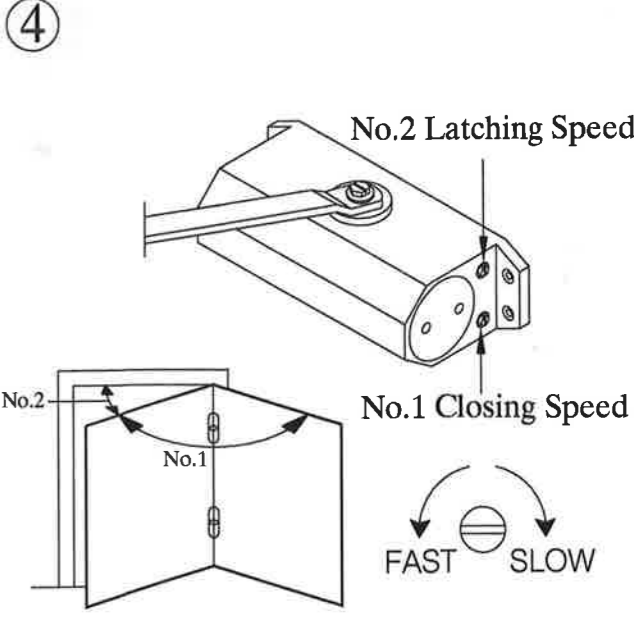
"Determine opening degree requirements 105 or 180 degrees, then select power requirement. This can be located on the template. Then use template to mark holes for closer body and arm pivot bracket"



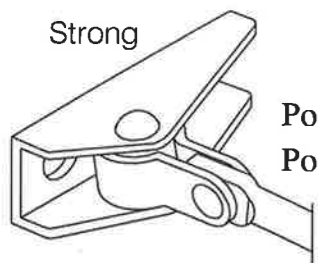
"Arm pivot bracket assembly into position and fix closer body to the marked holes ensuring that you select the position of the shoe, on the face of the frame, in the correct direction" Refer weak or strong.



Standard drawing

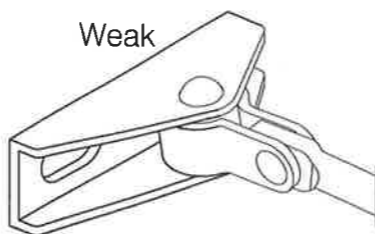


Adjust speed



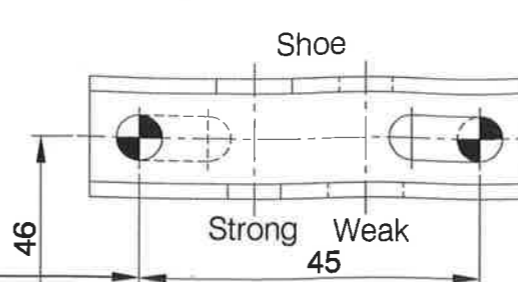
Strong

Position 1 force 3
Position 2 force 4



Weak

206



Shoe

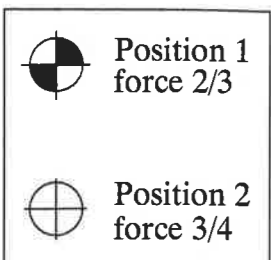
Strong Weak

DETERMINE POSITION OF SHOE FROM CHART OPPOSITE AND FIX ACCORDINGLY

UNDERSIDE OF FRAME



Speed Adjusting Valve



Position 1
force 2/3

Position 2
force 3/4

6-M5*P0.8

Use this side of template for clockwise opening door
(RIGHT HAND OPENING DOOR)

SET TO TOP OF DOOR



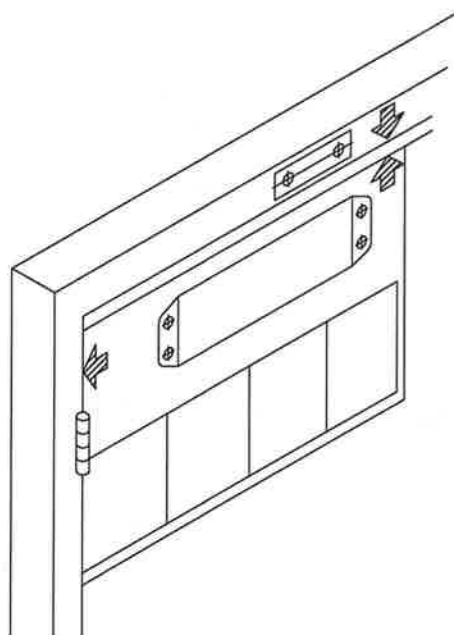
Ø2.5	Ø4.2
	M5

HINGE EDGE OF DOOR

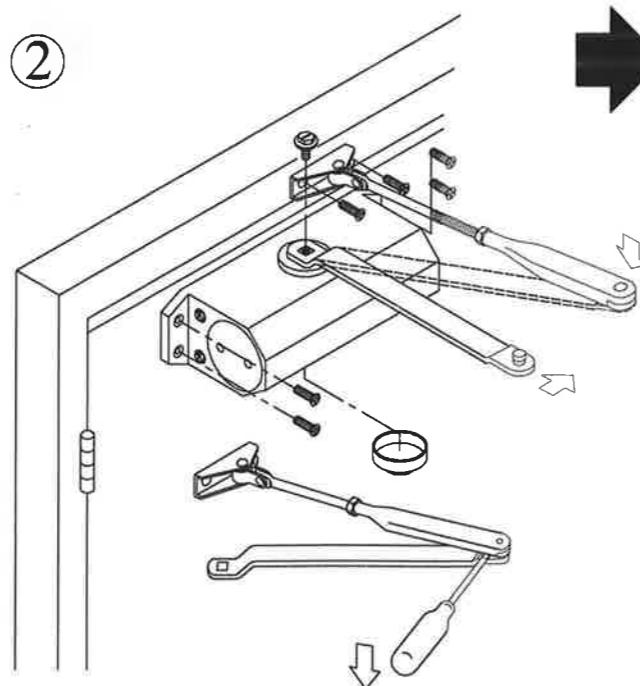
(Position 1) force 2/3 84mm
(Position 2) force 3/4 104mm

178

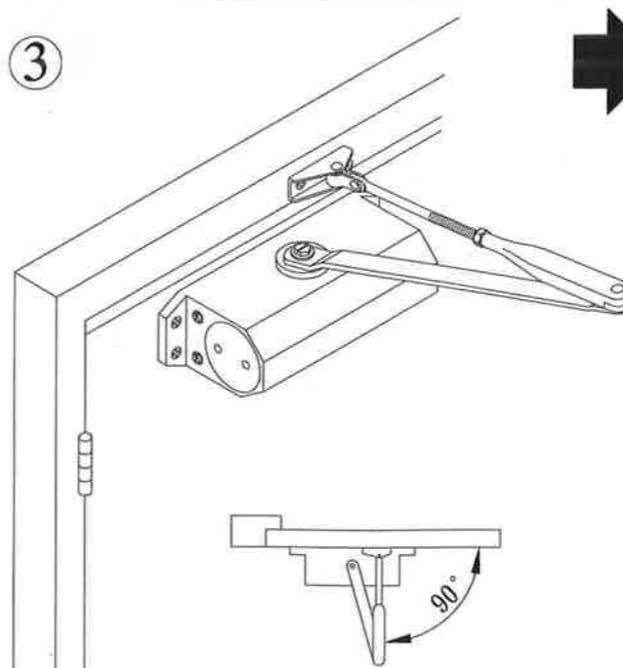
①



②



③

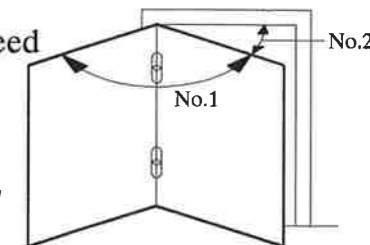
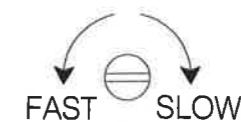


Standard drawing

④

No.1 Closing Speed

No.2 Latching Speed



Adjust speed

"Determine opening degree requirements 105 or 180 degrees, then select power requirement. This can be located on the template. Then use template to mark holes for closer body and arm pivot bracket"

"Arm pivot bracket assembly into position and fix closer body to the marked holes ensuring that you select the position of the shoe, on the face of the frame, in the correct direction" Refer weak or strong.